

# DTU Summer School on Modern Optimization in Energy Systems

## Conic Optimization: Part III

Pascal Van Hentenryck

# Goals of the Lecture

- ▶ Conic Optimization
  - Semi-Definite Programming over Complex Numbers

# AC Power Flows

$$S_i^g - S_i^d = \sum_{(i,j) \in E \cup E^R} S_{ij} \quad \forall i \in N$$

$$S_{ij} = \mathbf{Y}_{ij}^* \boxed{V_i V_i^*} - \mathbf{Y}_{ij}^* \boxed{V_i V_j^*} \quad (i, j) \in E \cup E^R$$

# Motivation

- ▶ Can we generalize SDP over complex matrices?
  - what is the equivalent of a symmetric matrix?
  - what is the equivalent of the SDP constraint?

# Hermitian Matrices



1855

# Hermitian Matrices



# Hermitian Matrices

- ▶ The Adjoint/Conjugate  $M^*$  of a complex matrix is defined as

$$[m_{ij}^*]^T$$

- ▶ A complex matrix is Hermitian if

$$M = M^*$$

- ▶ We use  $H_n$  to denote the set of  $n$  by  $n$  Hermitian matrices

- ▶ Inner product over  $\mathbb{C}^n$

$$\langle u, v \rangle = v^* u$$

# Hermitian Matrices

- ▶ Traces of Hermitian Matrices

$$\langle A, B \rangle = \text{Tr}(B^* A) = \sum_{i,j} a_{ij} b_{ij}^*$$

- ▶ Observe that

$$\langle A, B \rangle = \text{Tr}(B^* A) = \text{Tr}(BA) = \text{Tr}(AB)$$

- ▶ Property

$$(AB)^* = B^* A^*$$



# Hermitian Matrices

- Hermitian Matrices have only real eigenvalues

$$Ax = \lambda x$$

$$x^* Ax = \lambda x^* x$$

$$(x^* Ax)^* = (\lambda x^* x)^*$$

$$(x^* Ax)^* = x^* A^* x = \lambda^* x^* x$$

$$(\lambda - \lambda^*)(x^* x) = 0 \Rightarrow \lambda = \lambda^*$$

# Positive Semi-Definite Matrices

- ▶ An  $n$  by  $n$  Hermitian matrix  $M$  is positive semi-definitive if
  - $x^* M x \geq 0$  for all  $x \in \mathbb{C}^n$
  - all its eigenvalues are positive
  - $M = V V^*$  for some  $V$  in  $H_n$
- ▶ The last condition can be rephrased as
  - $M$  is positive semi-definite if and only if there exist vectors  $v_1, \dots, v_n \in \mathbb{C}^n$
  - such that

$$m_{ij} = \langle v_i, v_j \rangle$$

# Hermitian Matrix



# Complex Semi-Definite Programming

## ► Canonical Form

$$\begin{aligned} \min_{X \in H_n} \quad & Tr(CX) \\ \text{s.t.} \quad & Tr(A_i X) = b_i \quad 1 \leq i \leq m \\ & X \succeq 0 \end{aligned}$$



# Complex SDP

**Complex SDP can be written into Real SDP**

# From Complex SDP to Real SDP

- ▶ Let  $X$  in  $H_n$ . Define the matrix transformation

$$\mathcal{L}(X) = \begin{bmatrix} \Re(X) & -\Im(X) \\ \Im(X) & \Re(X) \end{bmatrix}$$

- ▶ where

$$\Re(X) = [\Re(x_{ij})]$$

$$\Im(X) = [\Im(x_{ij})]$$

# From Complex SDP to Real SDP

- Let  $X$  in  $H_n$ . Define the matrix transformation

$$\mathcal{L}(X) = \begin{bmatrix} \Re(X) & -\Im(X) \\ \Im(X) & \Re(X) \end{bmatrix} \quad \text{is symmetric}$$

- where

$$\Re(X) = [\Re(x_{ij})] \quad \text{is symmetric}$$

$$\Im(X) = [\Im(x_{ij})] \quad \text{is skew-symmetric} \quad (X = -X^T)$$

# From Complex SDP to Real SDP

► Let  $A, B$  in  $H_n$ .

$$\langle \mathcal{L}(A), \mathcal{L}(B) \rangle = \text{Tr} \left( \begin{bmatrix} \Re(B) & \Im(B) \\ -\Im(B) & \Re(B) \end{bmatrix} \begin{bmatrix} \Re(A) & \Im(A) \\ -\Im(A) & \Re(A) \end{bmatrix} \right)$$

$$\langle \mathcal{L}(A), \mathcal{L}(B) \rangle = 2\text{Tr}(\Re(A)\Re(B) + \Im(A)\Im(B)) = 2\langle A, B \rangle$$



# From Complex SDP to Real SDP

- ▶ Key idea
  - replace  $X$  by  $\mathcal{L}(\mathcal{X})$
- ▶ This requires
  - applying similar transformation to all constraints
  - adding constraints on the shape of the new matrix

# From Complex SDP to Real SDP

$$\begin{aligned} \min_{Y \in S_{2n}} \quad & Tr(\mathcal{L}(C)Y) \\ \text{s.t.} \quad & Tr(\mathcal{L}(A_i)Y) \leq 2b_i \quad 1 \leq i \leq m \\ & Y \succeq 0 \end{aligned}$$

$$\begin{aligned} \left\langle \begin{bmatrix} E_{ij} & 0 \\ 0 & -E_{ij} \end{bmatrix}, Y \right\rangle &= 0 \quad 1 \leq i, j \leq n \\ \left\langle \begin{bmatrix} 0 & E_{ij} \\ E_{ij} & 0 \end{bmatrix}, Y \right\rangle &= 0 \quad 1 \leq i, j \leq n \end{aligned}$$

►  $E_{ij}$  is a matrix that has a 1 in position  $(i,j)$  and  $(j,i)$  and is zero otherwise

# From Complex SDP to Real SDP

- ▶ What are the last two constraints ensuring?

$$Y = \begin{bmatrix} A & -B \\ B & A \end{bmatrix}$$

- ▶ Note that if I have  $Y$ , I can recover  $X$ .
  - How?

# From Complex SDP to Real SDP

- ▶ If  $X$  is feasible, then  $Y=L(X)$  is feasible
- ▶ If  $Y$  is feasible, then  $X=L^{-1}(Y)$  is feasible
- ▶ The objective value for the real problem is twice the objective value of the complex subproblem.

# From Complex SDP to Real SDP

- ▶ A complex eigenvector  $x$  for the complex subproblem is associated with the real eigenvector  $y$

$$y = \begin{pmatrix} \Re(x) \\ \Im(x) \end{pmatrix}$$

- ▶ A real eigenvector  $(r \ m)^T$  is associated with a complex vector

$$x = r + im$$